

# Overview over uncertainty estimation in neural networks

Maximilian Pintz | Fraunhofer IAIS | 19.10.2022

# **Deep Learning**

#### Deep neural networks

- Versatile systems for modeling complex patterns in data
- Learn from given data examples (training data) with the ability to generalize to new (unseen) data
- Successful across a large bandwidth of applications



[1] Input (e.g. street scene recording)

#### Goal: Extract patterns from data records



Deep neural network



Output pattern (e.g. position of cars)



**References:** [1] Geiger, A., Lenz, P., Stiller, C., & Urtasun, R. (2013). Vision meets robotics: The kitti dataset. The International Journal of Robotics Research, 32(11), 1231-1237. Image taken from the 2d object detection dataset. [2] Magnus Wrenninge and Jonas Unger. "Synscapes: A Photorealistic Synthetic Dataset for Street Scene Parsing". arXiv:1810.08705. Image source: "Synscapes Examples", 7DLabs, URL: <u>https://7dlabs.com/synscapes-examples</u> [3] "Objects detected with OpenCV's Deep Neural Network module (dnn) by using a YOLOV3 model trained on <u>COCO</u> dataset capable to detect objects of 80 common classes." by MThelier, CC BY-SA 4.0 [3] Alexander Selvikvag Lundervold and Arvid Lundervold. "An overview of deep learning in medical imaging focusing on MRI". In: Zeitschrift für Medizinische Physik 29.2 (2019), pp.102–127.



# **Motivation**

#### How reliable are deep neural networks?

Deep neural networks are increasingly employed in safety-critical systems (e.g. autonomous vehicles, medical diagnosis)

Failure of these systems potentially has severe consequences

 $\Rightarrow$  Risk mitigation and an assessment of their reliability are needed

Deep neural networks are impacted by **uncertainties** 

- Uncertainty: limited knowledge about the task or random factors that impact model performance
- Assessing and handling uncertainties is crucial for building reliable systems

#### Tesla Autopilot System Found Probably at Fault in 2018 Crash

The National Transportation Safety Board called for improvements in the electric-car company's driver-assistance feature and cited failures by other agencies.









# **Sources of uncertainty**

Lack of training data

Uncertainty: Have we supplied our model with enough training data?

Impact: Lack of training data can worsen model performance, especially performance on uncommon inputs



References: [1] Braun et al. "EuroCity Persons: A Novel Benchmark for Person Detection in Traffic Scenes." In IEEE Transactions on Pattern Analysis and Machine Intelligence, 2019



# **Sources of uncertainty**

Data uncertainty

Uncertainty: Is the data the model learns from clear without ambiguity?

Impact: Uncertainty in the input can propagate to the output

#### Examples:

- Coin toss
- Sensor noise
- Weather conditions, occluded sensors, ...
- Annotation error / ambiguity





References: [1] Geiger et al. (2013). Vision meets robotics: The kitti dataset. The International Journal of Robotics Research, 32(11), 1231-1237. Image taken and modified from the 2d object detection dataset.



# **Uncertainty Estimation**

Observations:

- Deep neural networks are impacted by several uncertainties, which cause changes in the end result and impact task performance
- Many of these uncertainties are inherent to the process and cannot (practically) be reduced, especially in open-world scenarios

**Uncertainty estimation:** Quantifying the impact of uncertainties on the end result

- Tries to answer: "How certain is the model of the prediction?"
- Understand better whether model outputs can be trusted



Uncertainty Estimation in Steering Angle Prediction [1]

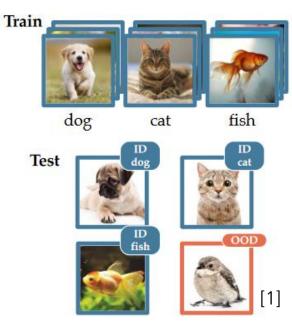
**References:** [1] Loquercio, A., Segu, M., & Scaramuzza, D. (2020). A general framework for uncertainty estimation in deep learning. *IEEE Robotics and Automation Letters*, 5(2), 3153-3160.



# **Applications of uncertainty estimation**

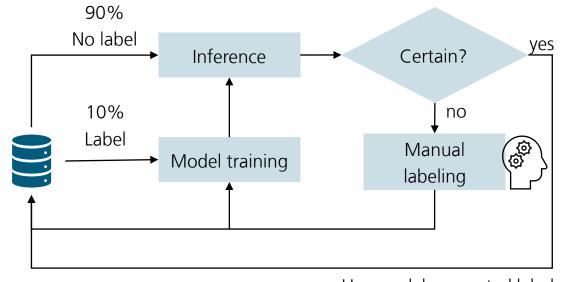
#### **Out-of-distribution detection**

Identifying "unusual" inputs, in particular inputs that do not stem from the training data distribution



#### **Active Learning**

Selecting uncertain prediction for manual labeling



Use model generated label

References: [1] Yang et al. "Generalized Out-of-Distribution Detection: A Survey", arxiv:2110.11334

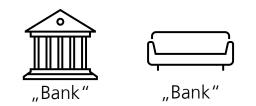


# **Applications of uncertainty estimation**

#### **Computer Vision**



#### **Natural Language Processing**



"I am quite sure that A equals B."

#### **Further applications**

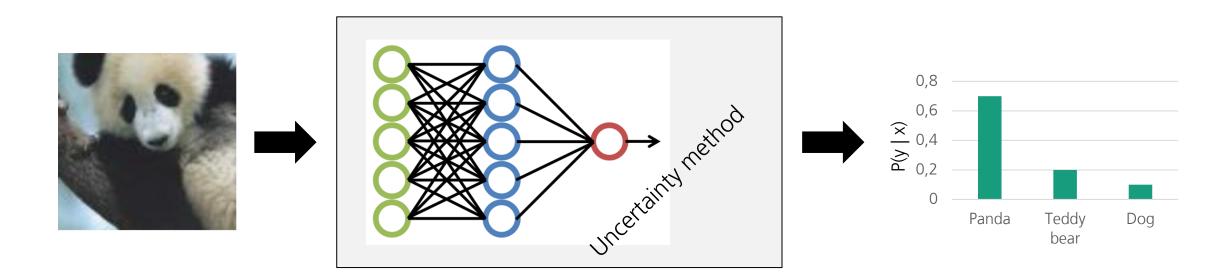
Reinforcement learning, Robotics, Meta-learning, Few-shot-learning ...



Probabilistic Deep Learning

# In probabilistic deep learning, the neural network computes a probability distribution instead of a single output

Estimation of the probability distribution p(y | x) over model outputs that captures (predictive) uncertainty





# **Types of uncertainty** Aleatoric and epistemic

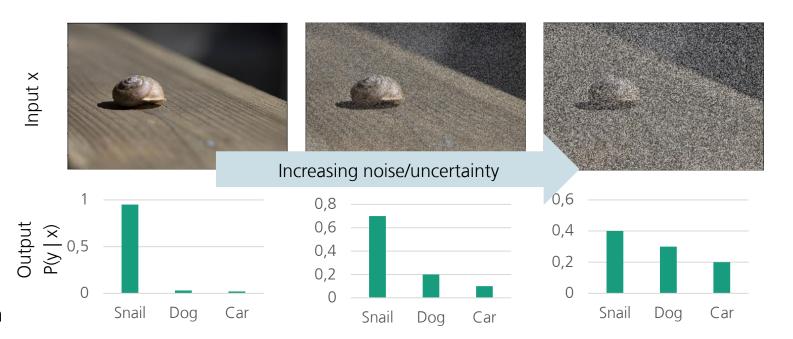
#### **Aleatoric uncertainty**

Inherent (non-reducible) randomness in the learning process [1], in particular the data

Examples:

- Annotation error / ambiguity
- Sensor noise
- Corruptions

Typically modeled via a probability distribution on model outputs  $p(y \mid x)$ 



**References:** [1] Hüllermeier, E., & Waegeman, W. (2021). Aleatoric and epistemic uncertainty in machine learning: An introduction to concepts and methods. *Machine Learning*, *110*(3), 457-506. [2] Kohl. et al. "A Probabilistic U-Net for Segmentation of Ambiguous Images", NIPS 2018



# **Types of uncertainty** Aleatoric and epistemic

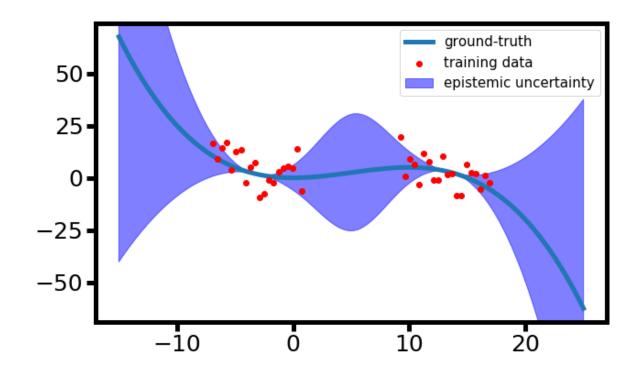
#### **Epistemic uncertainty**

Lack of knowledge about the perfect model ("Bayes-predictor")

#### Examples:

- Model mismatch
- Lack of training data
- Hyperparameter tuning
- Data shuffling, augmentation, splits

Typically modeled via distributions over models (most commonly model parameters p(w))





# **Evaluation of uncertainty estimates**

Desiderata for "good" uncertainty estimates

#### **Desired properties of "good" uncertainty estimates**

Alignment of predicted probability distributions with given data

- Alignment per data point (Proper Scoring Rules)
- Alignment over data subsets (Calibration)

#### Application-specific properties

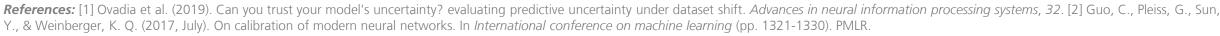
- Distinguishing between in- and out-of-distribution data points, between true & false positives, ... (Entropy, AUC, ...)

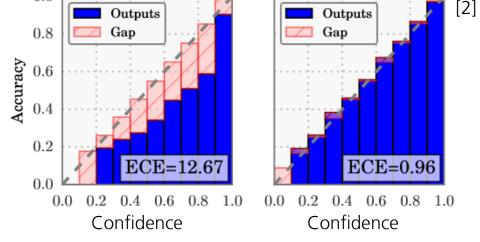
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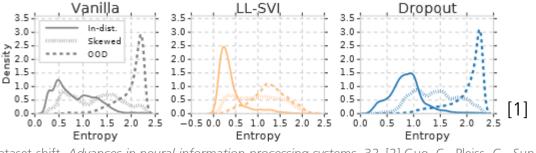
- Performance in active learning tasks, ...

Qualitative properties

- Increasing uncertainty under data-shift, ...



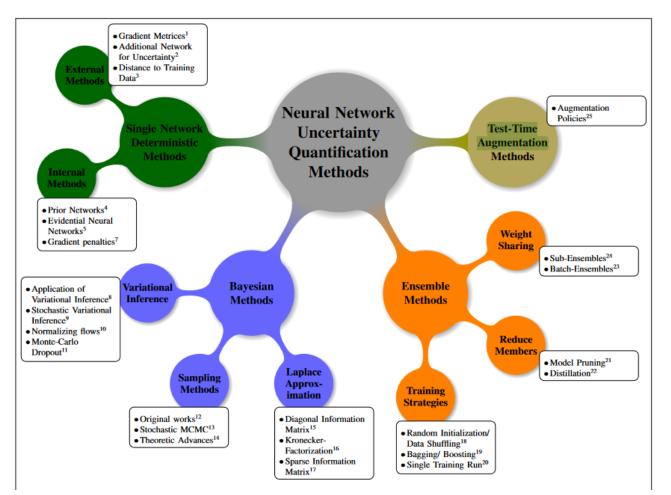






## Probabilistic Deep Learning

- 1. Direct parametrization
- 2. Bayesian Inference
- 3. Ensembling
- 4. Recalibration
- 5. (Test-time augmentation)



References: [1] Gawlikowski et al. (2021). A survey of uncertainty in deep neural networks. arXiv preprint arXiv:2107.03342.



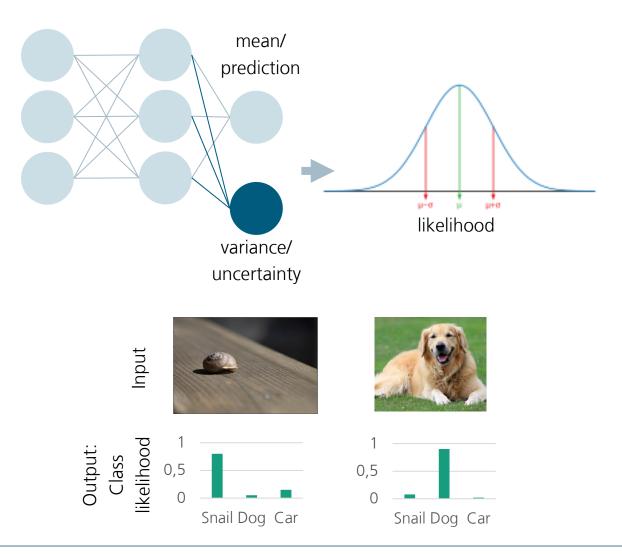
Direct parametrization

#### Concept:

 Neural network computes parameters of a probability distribution in one forward pass (no sampling)

#### Simple variant: "Likelihood parametrization"

- Adding additional neurons to the output layer for computing distribution parameters (e.g. mean and variance)
- Model outputs the "likelihood" (a distribution over model outputs), which describes aleatoric uncertainty
- Training: Maximize the likelihood over training data





Direct parametrization

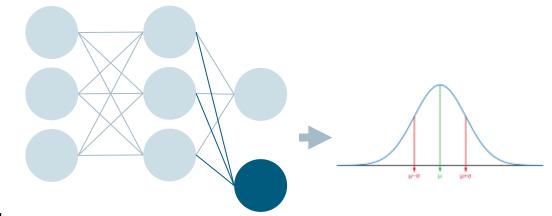
#### Likelihood parametrization

Pro:

- Low compute overhead at training and inference
- Uncertainty estimates with a single forward pass, no sampling required
- Easy to combine with other uncertainty methods
- Typically easy to implement (depends on the complexity of the distributions)

#### Cons:

- Only models aleatoric uncertainty (in particular does not capture out-of-distribution uncertainty)
- Requires change of architecture/loss (although typically just the output layer)
- Parametric assumption

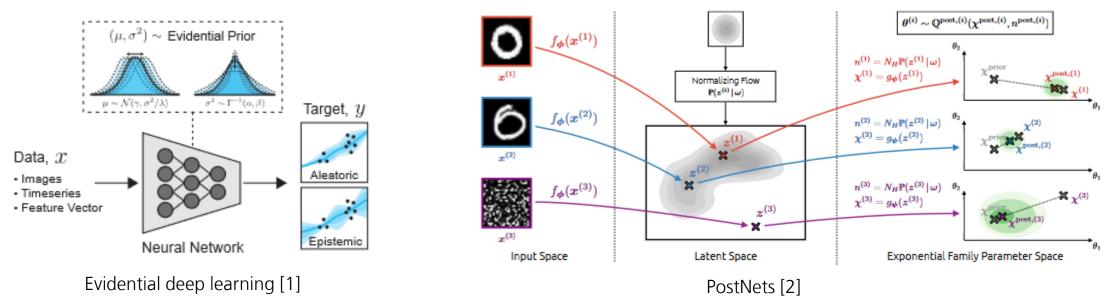




Direct parametrization

#### **Current methods**

Joint estimation of aleatoric and epistemic uncertainty with a single forward pass ... ... but increased complexity in terms of implementation and compute overhead



**References:** [1] Amini et al. (2020). Deep evidential regression. Advances in Neural Information Processing Systems, 33, 14927-14937. [2] Charpentier et al. (2021, September). Natural Posterior Network: Deep Bayesian Predictive Uncertainty for Exponential Family Distributions. In *International Conference on Learning Representations*.



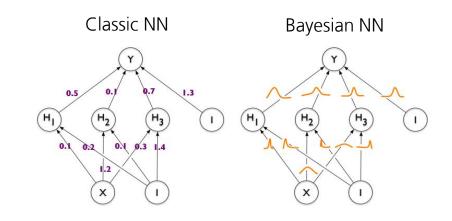
Bayesian Inference for Deep Learning

#### **Bayesian inference**

Concept:

- Theoretical framework for incorporating epistemic uncertainty
- Extension of likelihood parametrization
- Derives two central distributions
  - Posterior distribution p(w | D) for epistemic uncertainty: distribution on model parameters w given training data D
  - Predictive posterior: p(y | x, D) to jointly capture epistemic and aleatoric uncertainty: distribution on model outputs y given an unseen input x, and training data D

For neural networks, it is infeasible to compute the exact posterior and predictive posterior => Approximate methods are needed (Discussed in the field "approximate Bayesian inference")





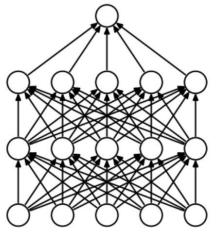
Thomas Bayes

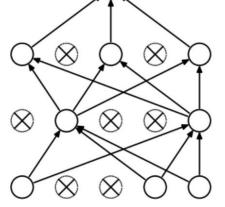


#### **Dropout mechanism** [1]

Concept:

- Commonly used method for mitigating ", overfitting", the problem that a neural network learns the training data by heart instead of the underlying patterns
- Randomly deactivate neurons during training
- Training an ensemble of multiple, simpler sub-networks, instead of a complex single network
- Leave dropout inactive during inference





(a) Standard Neural Net

(b) After applying dropout.

**References:** [1] Nitish Srivastava, Geoffrey Hinton, Alex Krizhevsky, Ilya Sutskever, and Ruslan Salakhutdinov. 2014. Dropout: a simple way to prevent neural networks from overfitting. J. Mach. Learn. Res. 15, 1 (January 2014), 1929–1958.

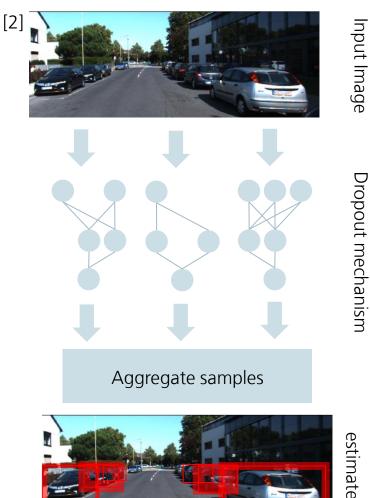


MC Dropout

#### MC Dropout [1]

Concept:

- Leave dropout activated during inference
- Collect multiple predictions from different sub-networks for fixed input
- Compute sample statistics (mean, variance) for uncertainty estimation
- Approximation of Bayesian inference



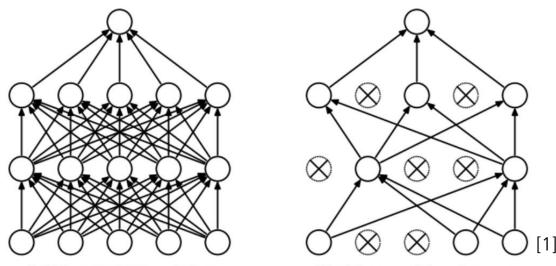
Uncertainty estimates

References: [1] Gal, Y., & Ghahramani, Z. (2016, June). Dropout as a bayesian approximation: Representing model uncertainty in deep learning. In international conference on machine learning (pp. 1050-1059). PMLR. [2] Geiger et al. (2013). Vision meets robotics: The kitti dataset. The International Journal of Robotics Research, 32(11), 1231-1237. Image taken and modified from the 2d object detection dataset.



#### Pro:

- Widespread method
- Applicable to a broad range of architectures
- Easy to implement
- Low computational overhead during training
- Captures epistemic uncertainty



(a) Standard Neural Net

(b) After applying dropout.

#### Con:

- Does not model input-dependent aleatoric uncertainty
- But can be extended, e.g. by combining with ensembling or likelihood parametrizations
- Requires multiple forward passes during inference
- Approximation errors

References: [1] Srivastava et al. 2014. Dropout: a simple way to prevent neural networks from overfitting. J. Mach. Learn. Res. 15, 1 (January 2014), 1929–1958.

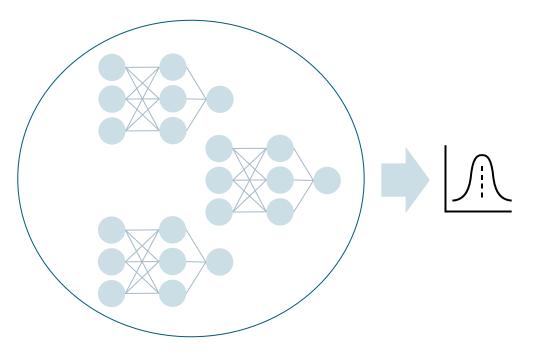


#### Deep Ensembles [1]

Concept: Combining multiple (uncertainty-estimating) models into a stronger one (ensembling)

#### Pro:

- Easy to implement
- Captures epistemic and aleatoric uncertainty
- Easier attribution of uncertainties to concrete sources
- Easy to apply to different architectures and use cases (no change in architecture needed)



Con: High compute-overhead at training and inference (n models)

References: [1] Lakshminarayanan, B., Pritzel, A., & Blundell, C. (2017). Simple and scalable predictive uncertainty estimation using deep ensembles. Advances in neural information processing systems, 30.

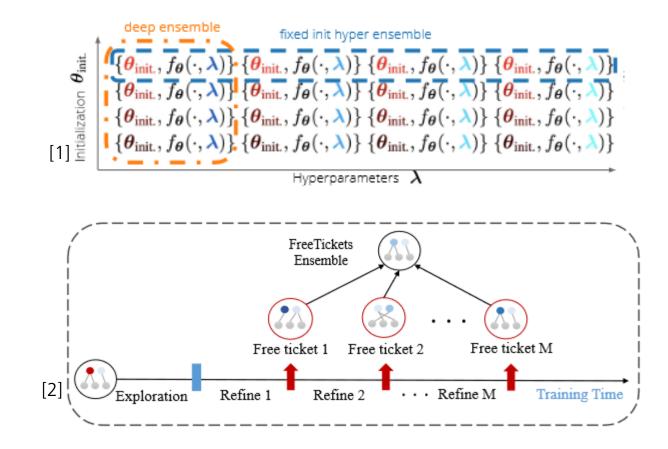


#### **Current methods**

Increased diversity of the ensembles

- Ensembles of models with different hyperparameters ("Hyper-deep ensembles")
- Ensembles of models with different architectures (combination with NAS)

Efficient Ensembles (e.g. dropout, sparse networks, ...)



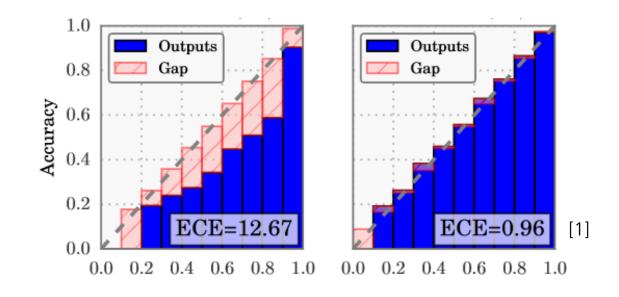
**References:** [1] Wenzel, F., Snoek, J., Tran, D., & Jenatton, R. (2020). Hyperparameter ensembles for robustness and uncertainty quantification. Advances in Neural Information Processing Systems, 33, 6514-6527. [2] Liu, S., Chen, T., Atashgahi, Z., Chen, X., Sokar, G., Mocanu, E., ... & Mocanu, D. C. (2021). FreeTickets: Accurate, Robust and Efficient Deep Ensemble by Training with Dynamic Sparsity. arXiv preprint arXiv:2106.14568.



#### **Uncertainty estimation methods for neural networks** Recalibration

Concept:

- Map given (uncalibrated) uncertainty estimates (e.g. densities, confidence values) to calibrated ones using a (simple) auxiliary model (Platt/temperature scaling, histogram binning)
- Optimizing a calibration measure on a validation dataset



References: [1] Guo, C., Pleiss, G., Sun, Y., & Weinberger, K. Q. (2017, July). On calibration of modern neural networks. In International conference on machine learning (pp. 1321-1330). PMLR.



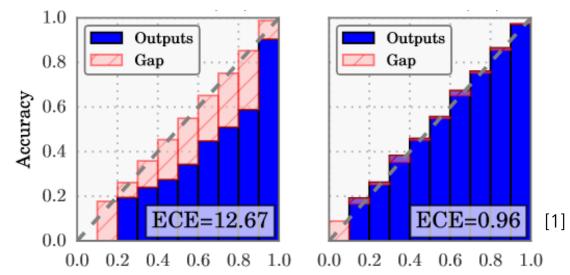
### **Uncertainty estimation methods for neural networks** Recalibration

#### Pro

- Can be applied after training, black-box access to the model
- Easy-to-implement
- Low computational overhead

#### Con

- Requires (uncalibrated) uncertainty estimates and validation data
- Calibration may overfit to validation dataset (often bad calibration on out-of-distribution inputs)
- Does not model epistemic uncertainty



References: [1] Guo, C., Pleiss, G., Sun, Y., & Weinberger, K. Q. (2017, July). On calibration of modern neural networks. In International conference on machine learning (pp. 1321-1330). PMLR.



# Conclusion

- Deep learning is affected by uncertainties
- Uncertainty estimation has several applications and plays an inportant role in reliability assessment
- Uncertainties are modeled via probability distributions
- Two types of uncertainty: aleatoric and epistemic
- Evaluation of uncertainty estimates: proper scoring rules, calibration, out-of-distribution separation, ...
- Probabilistic deep learning: different methods for uncertainty estimation in neural networks, each with their own strengths and weaknesses

